Table of Contents

| 1. Assembling the Motor Unit's Parts | 2 |
|--|------------------------------|
| 2. Assembling the Diaphragms | 3 |
| 3. Assembling the Active Brush | 3 |
| 4. Assembling the Motor Unit | 5 |
| 5. Assembling the Drive System and Side Cover | 6 |
| 6. Assembling the Non-driving Track and Side Cover | Error! Bookmark not defined. |
| 7. Assembling the Floating Cable | 9 |
| 8. Positioning the Float | 11 |
| 9. Positioning the Brush Covers | 12 |
| 10. Assembling the Outer Casing | 13 |
| 11. Assembling the Impeller Cover | 14 |
| 12. Assembling the Handle | 15 |
| 13 Assembling the Brushes | 16 |



1. Assembling the Motor Unit's Parts



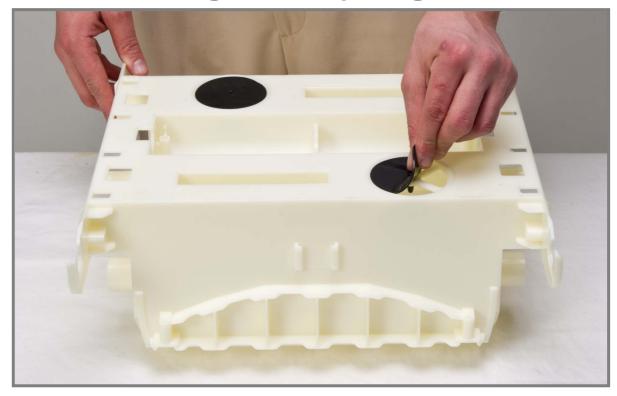
Step 1.1 Secure the impeller with a M4X25 screw, for your safety make sure you use a screwdriver.



Step 1.2 Secure the impeller protector cylinder with 4 KA50X12 screws.

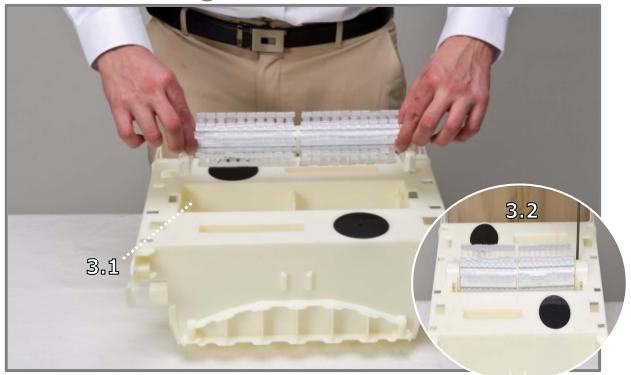


2. Assembling the Diaphragms



Step 2.1 Insert two diaphragms.

3. Assembling the Active Brush



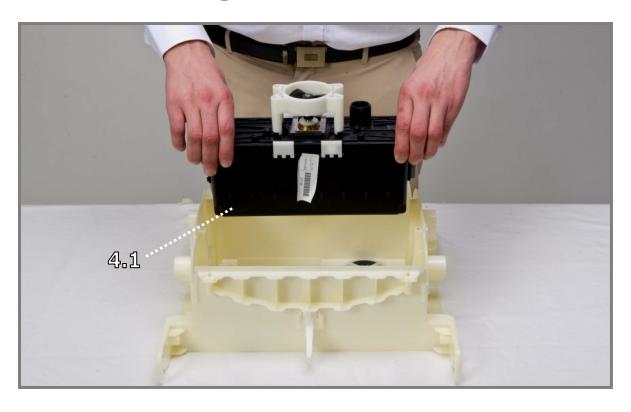
Step 3.1Place the Active
Brush in its place.

Step 3.2 Secure the Active Brush in place with 4X KA50X20 screws.





4. Assembling the Motor Unit



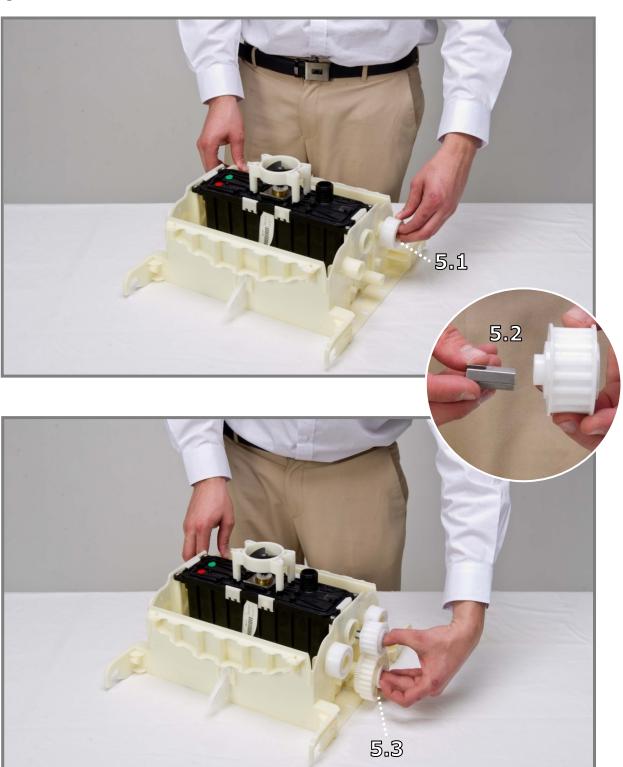
Step 4.1
There is only
one way to place
the motor unit in
the frame.



Step 4.2 Secure the motor unit to the frame with 4X KA50X20 screws.



5. Assembling the Drive System and Side panel



Step 5.1
Place 4 guide
wheels on both
sides of the motor
shaft on both
sides of the robot

Step 5.2
Put 2 hexagon
adaptors into the
pulley on both
sides of the robot.

Step 5.3
Put the pulley and the Active Brush gear in their places on both sides of the robot.



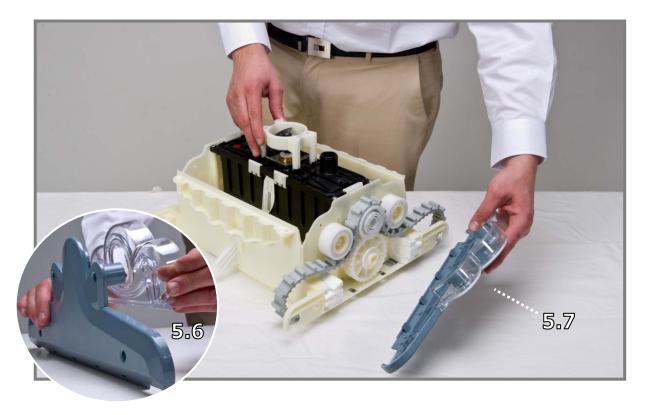


Step 5.4

Place the track in its place as shown on both sides of the robot.

Step 5.5

Place the side floats on both sides of the robot



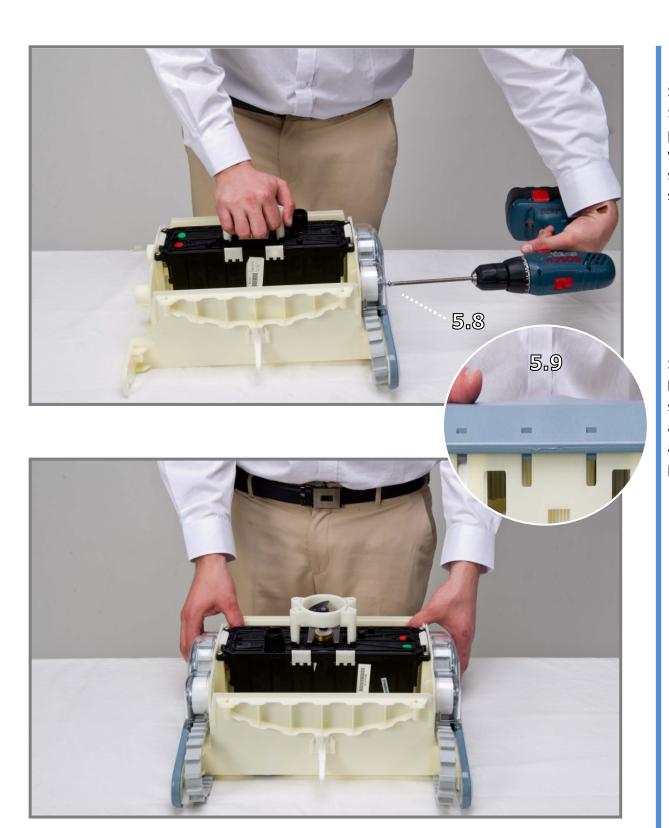
Step 5.6

Assemble the 2 track safety covers on the side panels.

Step 5.7

Put the side panels into place on both sides of the robot.



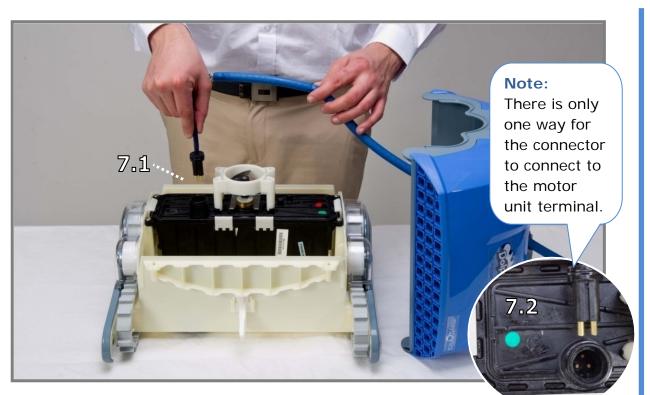


Step 5.8
Secure the side panels in place with 4 KA50X20 screws on both sides of the robot.

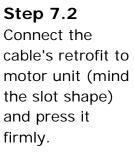
Step 5.9
Make sure the side panel clips are in their places as shown in the picture

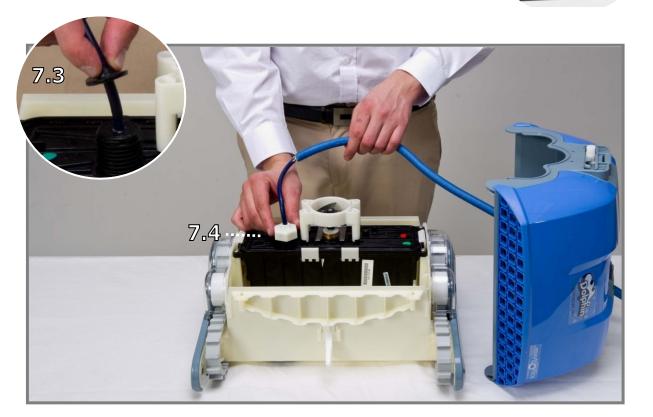


6. Assembling the Floating Cable



Step 7.1 Insert the floating cable to the motor unit.

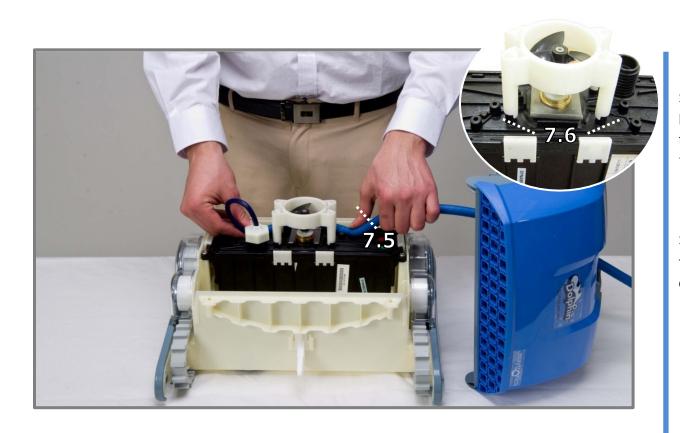




Step 7.3
Press the seal firmly to the terminal.

Step 7.4 Tighten the nut properly by hand.

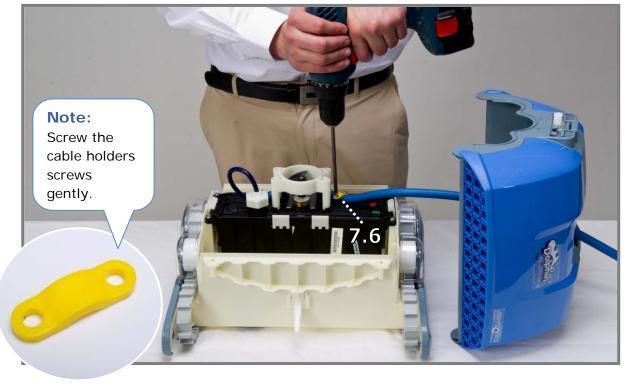




Step 7.5Position the floating cable on the motor unit.

Step 7.6

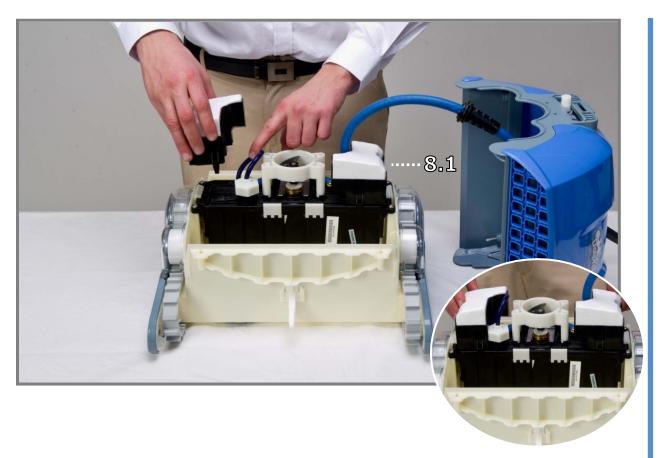
The cable position on the motor unit



Step 7.6 Secure the cable holders with 4X KA50X12 screws.



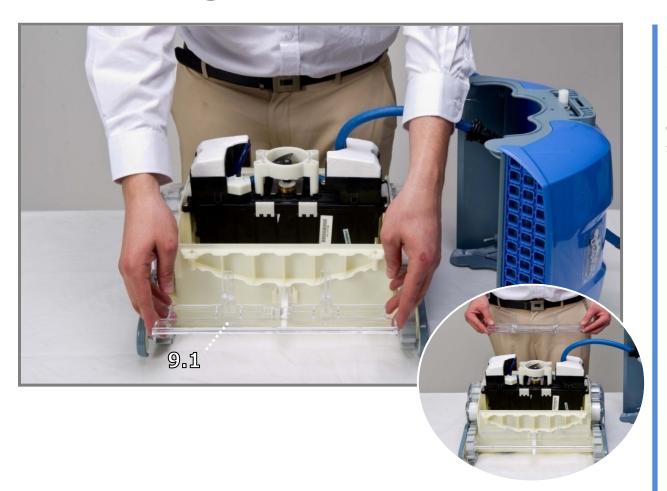
8. Positioning the Float



Step 8.1 Place the 2 floats on the motor unit.



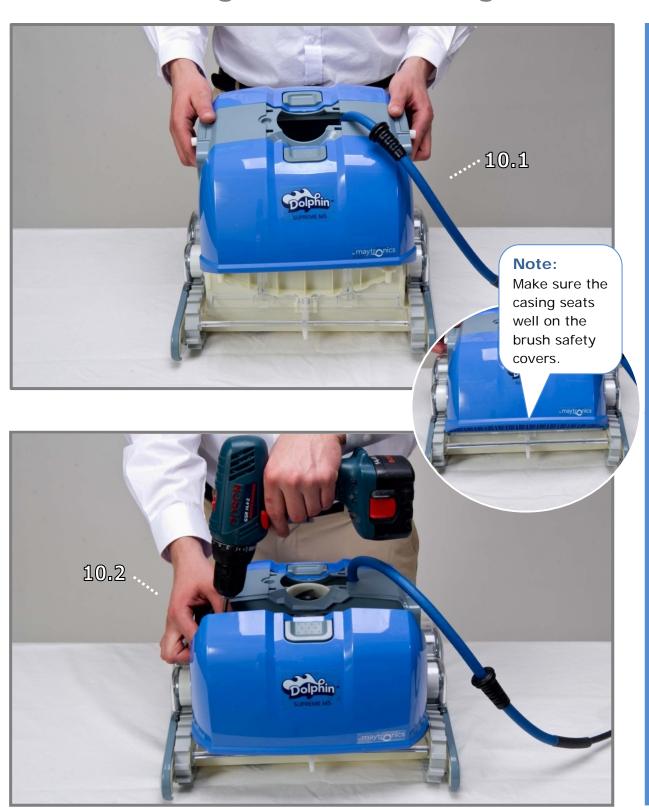
9. Positioning the Brush Covers



Step 9.1
Position the 2
brush safety
covers on both
sides of the robot



10. Assembling the Outer Casing

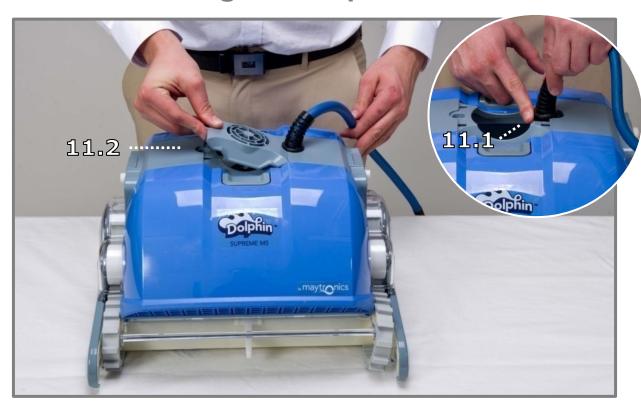


Step 10.1
Place the outer casing on the frame.

Step 10.2 Secure the outer casing to the frame with 4X KA50X20 screws.



11. Assembling the Impeller Cover



Step 11.1
Place the cable support in its place on the outer casing before closing the impeller cover.

Step 11.2
Position the impeller cover diagonally on the outer cover.



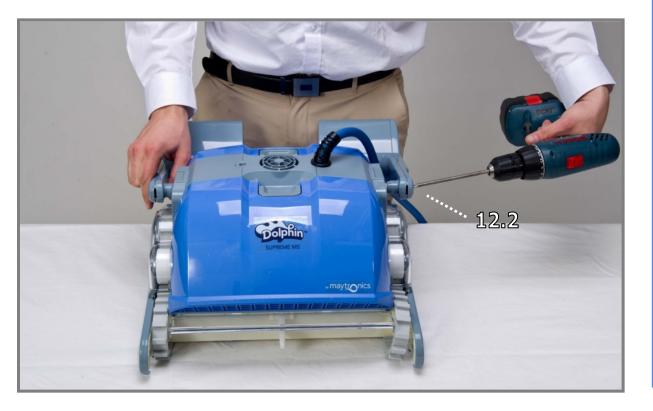
Step 11.3 Secure the impeller cover with a KA50X12 screw.



12. Assembling the Handle



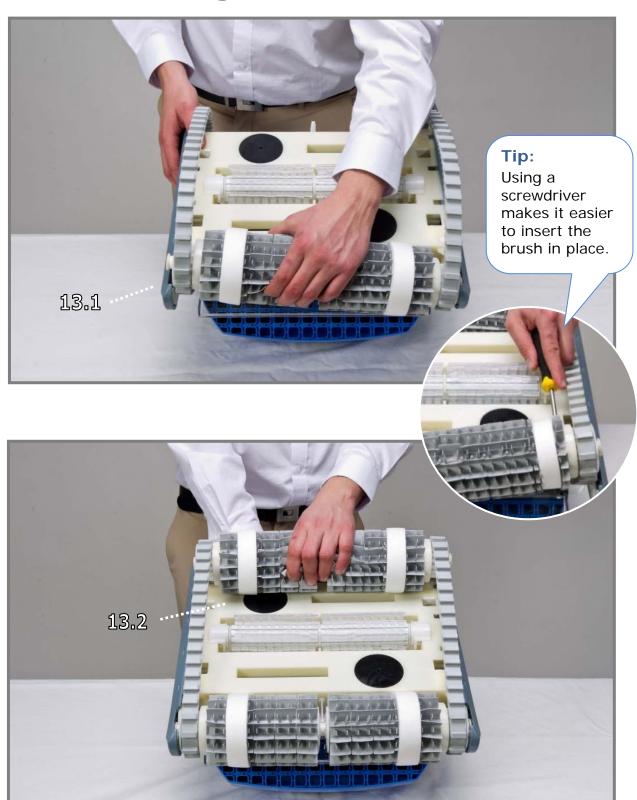
Step 12.1 Position the handle.



Step 12.2 Secure the handle in place with 2 KA50X20 screws.



13. Assembling the Brushes



Step 13.1 Place one brush in place.

Step 13.2
Place the second brush in its place by pulling it strongly towards you.



Table of Contents

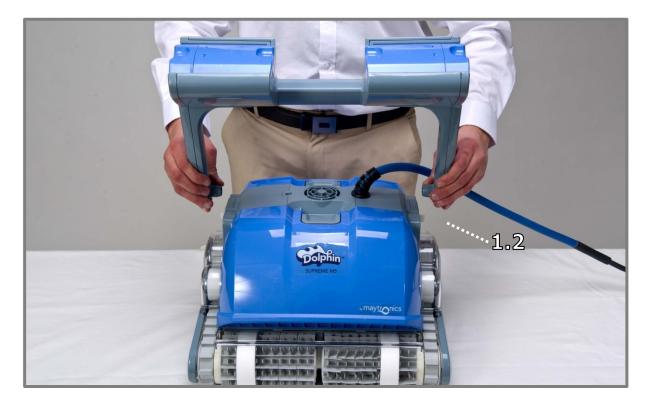
| 1. Dismantling the Handle | 2 |
|-----------------------------------|----|
| 2. Dismantling the Impeller Cover | |
| 3. Dismantling the Outer Casing | 4 |
| 4. Dismantling the Cable | 5 |
| 5. Disassembling the Motor Unit | 6 |
| 6. Dismantling the Side Panels | 7 |
| 7. Dismantling the Drive System | 8 |
| 8. Dismantling the Brushes | 9 |
| 9. Dismantling the Diaphragms | 10 |



1. Dismantling the Handle



Step 1.1 Unscrew the 2 screws holding the handle in place.



Step 1.2Take the handle off.



2. Dismantling the Impeller Cover



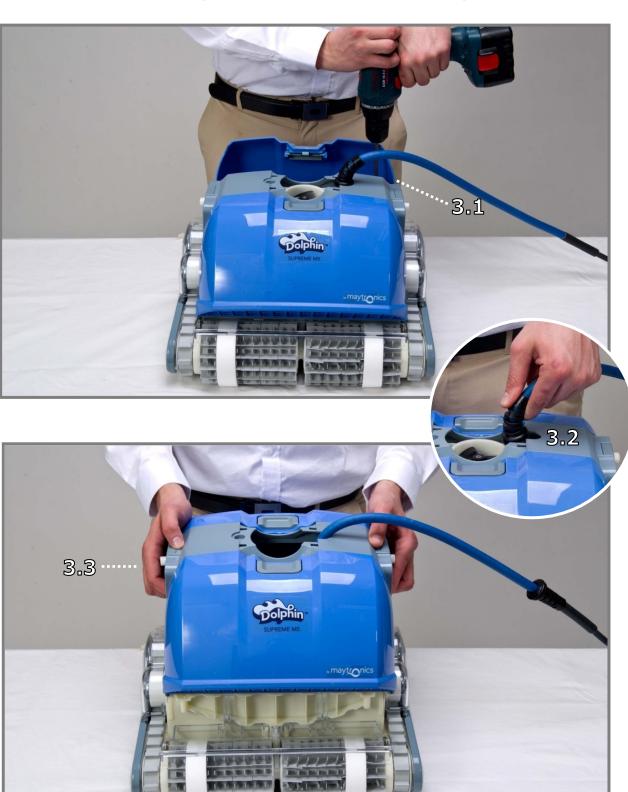
Step 2.1
Unscrew the screw holding the impeller cover in place.



Step 2.2
Lift the impeller cover up from one side and then take it off.



3. Dismantling the Outer Casing



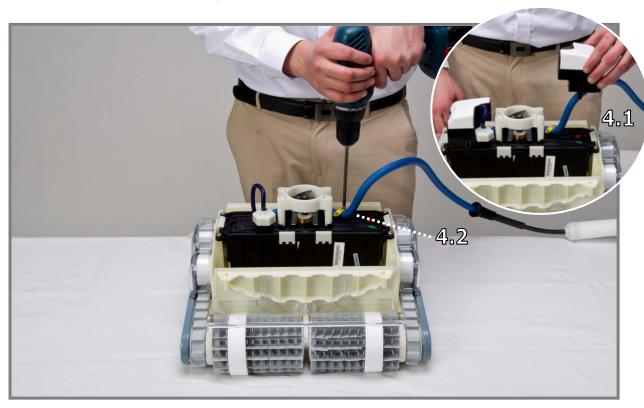
Step 3.1
Unscrew the 4
screws holding
the outer casing
in place.

Step 3.2
Remove the black grommet before taking off the outer casing.

Step 3.3
Hold the outer casing on both sides and pull it up.

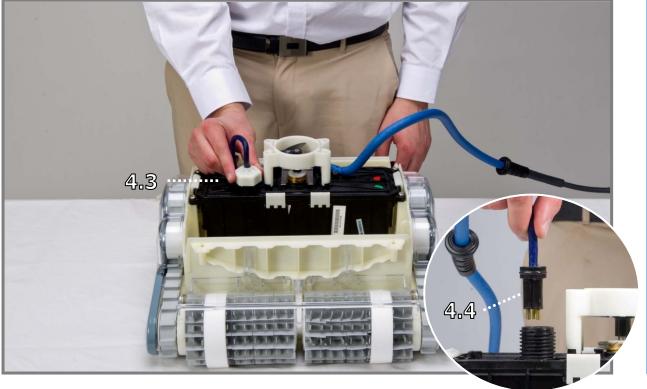


4. Dismantling the Cable



Step 4.1Remove 2 floats from the motor unit.

Step 4.2
Unscrew the 4
screws securing
the cable holder.

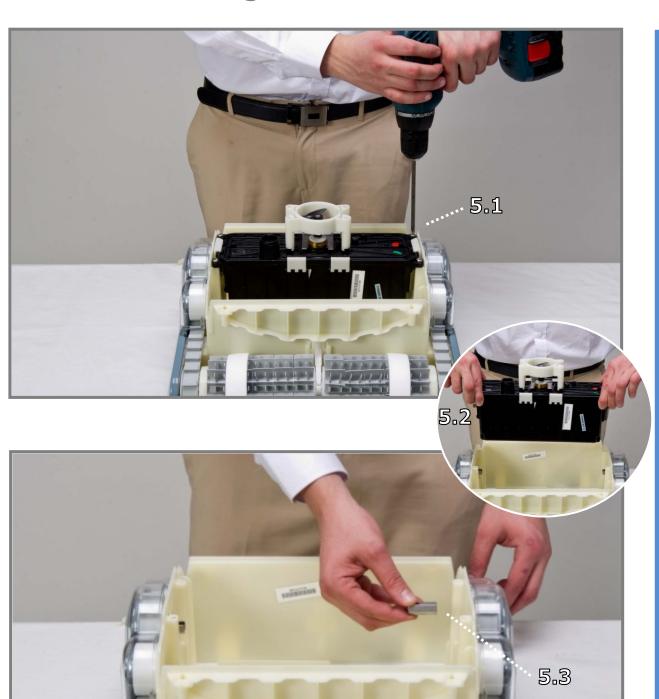


Step 4.3 Unscrew the cable from the motor unit.

Step 4.4
Unplug the cable.



5. Disassembling the Motor Unit



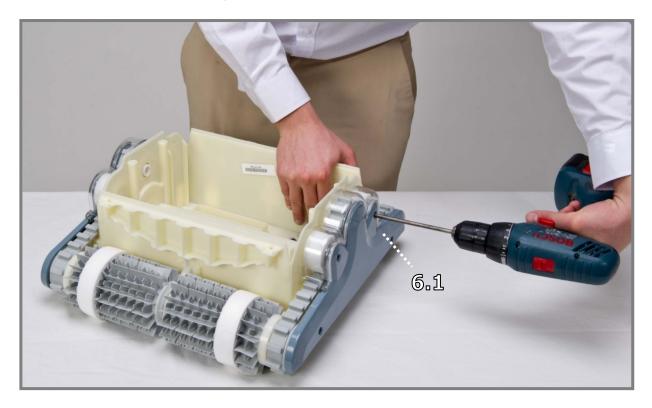
Step 5.1
Unscrew the 4
screws securing
the motor unit
to the frame.

Step 5.2
Remove the motor unit

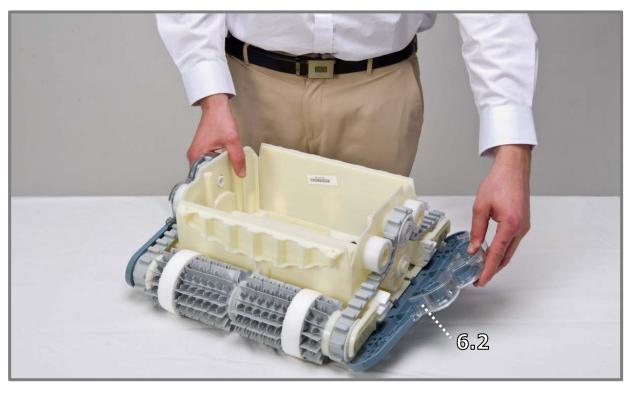
Step 5.3
Remove the 2
hexagon
adapters.



6. Dismantling the Side Panels



Step 6.1 Unscrew the 4 screws holding each panel in place.



Step 6.2Pull the 2 side panels off.

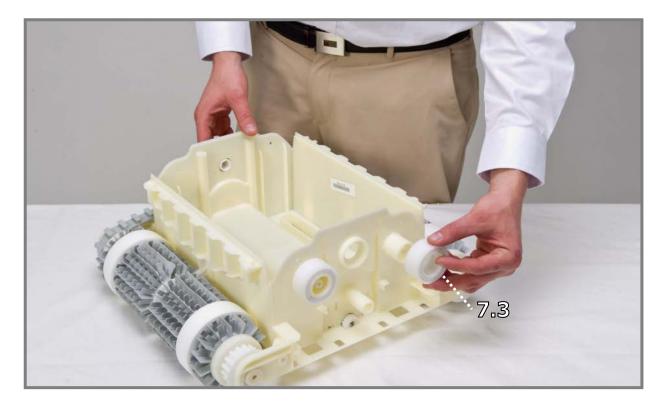


7. Dismantling the Drive System



Step 7.1
Remove the 2
side floats from
both sides of the
robot

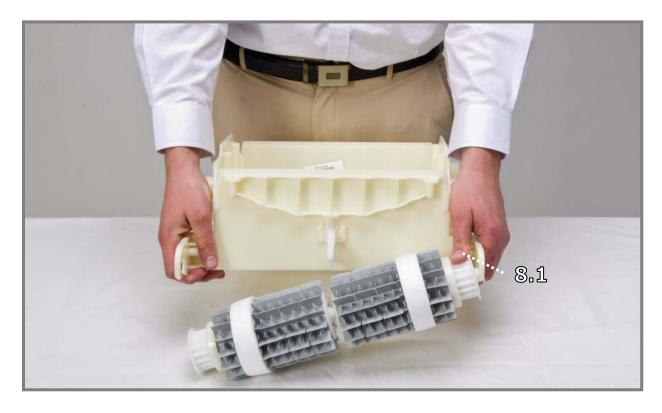
Step 7.2
Remove the pulley together with the track and Active
Brush's driving wheel from both sides of the robot.



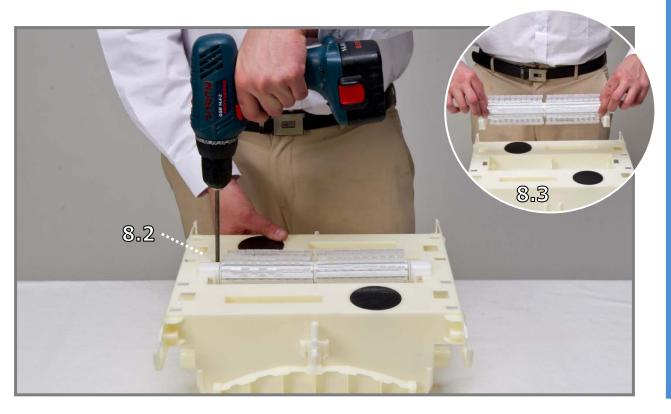
Step 7.3Remove the guide wheels.



8. Dismantling the Brushes



Step 8.1 Remove the brushes.

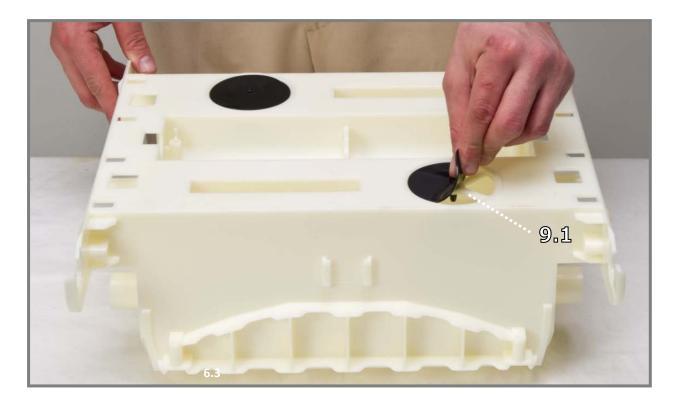


Step 8.2
Open the 4
screws holding
the active brush
in place.

Step 8.3Remove the Active Brush.



9. Dismantling the Diaphragms



Step 9.1 Remove the 2 diaphragms.

