Table of Contents

1. Assembling the Motor Unit's Parts	2
2. Assembling the Diaphragms	3
3. Assembling the Active Brush	4
4. Assembling the Motor Unit	5
5. Assembling the Driving System and Side Cover	6
6. Assembling the driving system and Side Cover on the other side of the robot	9
7. Assembling the Floating Cable	11
8. Positioning the Float	13
9. Positioning the Brush Covers	14
10. Assembling the Outer Casing	15
11. Assembling the Impeller Cover	16
12. Assembling the Handle	17
13. Assembling the Brushes	18



1. Assembling the Motor Unit's Parts



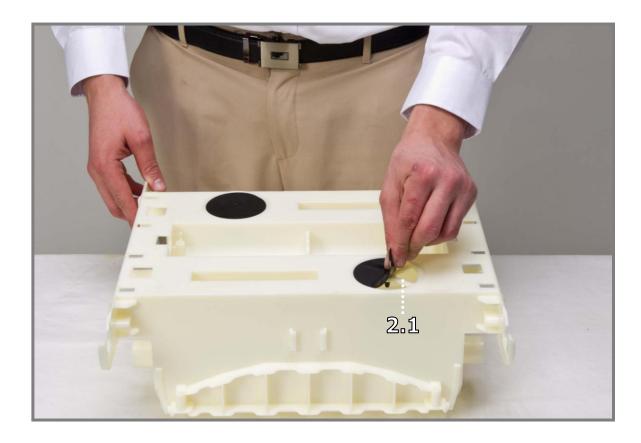
Step 1.1Secure the impeller with a 4X25 screw.



Step 1.2Secure the impeller protector cylinder with 4 KA50X12 screws.



2. Assembling the Diaphragms



Step 2.1 Insert two diaphragms.



3. Assembling the Active Brush



Step 3.1Place the Active
Brush in its place.

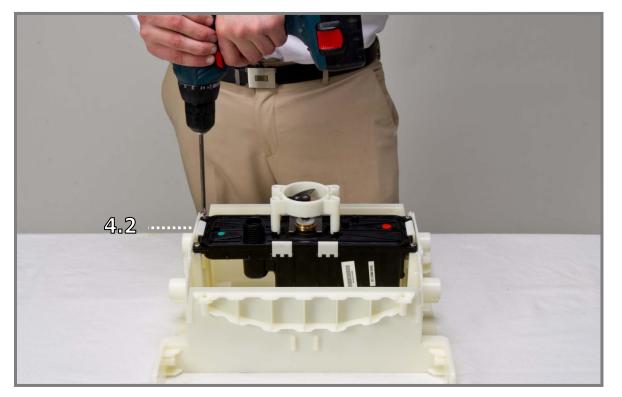
Step 3.2Secure the Active
Brush in place with
4X KA50X20
screws.



4. Assembling the Motor Unit



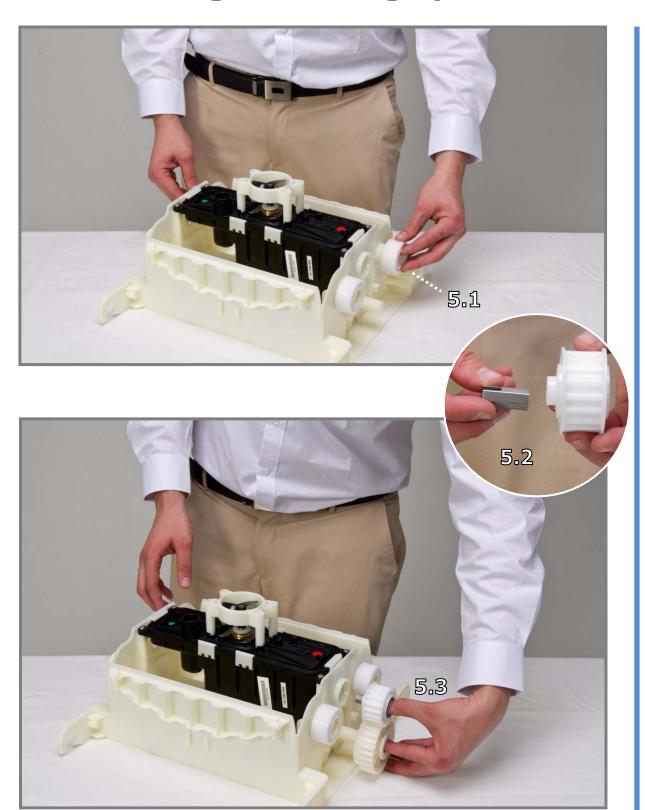
Step 4.1 There is only one way to place the motor unit in the frame.



Step 4.2 Secure the motor unit to the frame with 4X KA50X20 screws.



5. Assembling the Driving System and Side Cover



Step 5.1 Place the guide wheels on the side of the motor shaft.

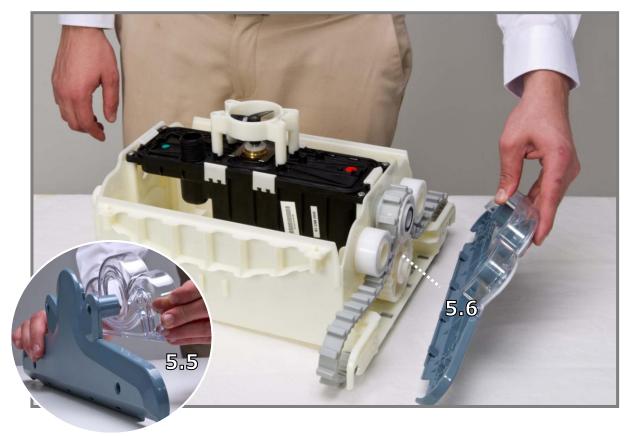
Step 5.2Put the hexagon adaptor into the pulley.

Step 5.3Put the pulley and the Active Brush gear in their places.





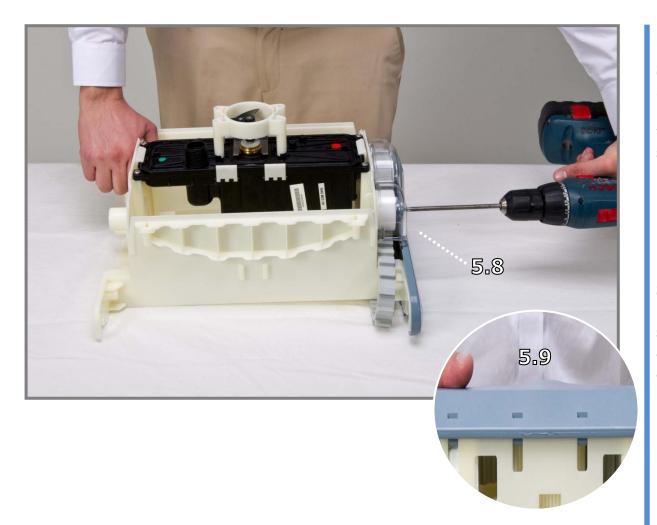
Step 5.4Place the track in its place as shown on both sides of the robot.



Step 5.5Assemble the track safety cover on the side panel.

Step 5.6Put the side panel into its place.



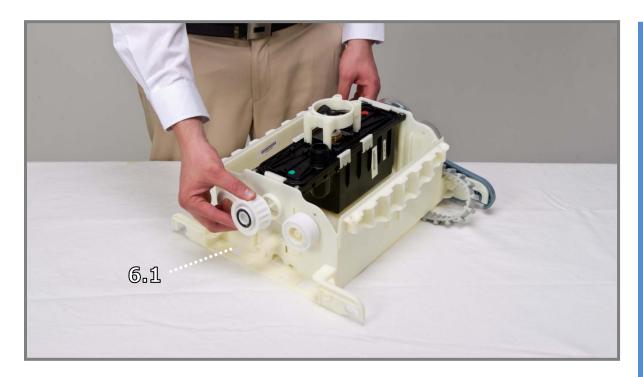


Step 5.8Secure the side panel in place with 4 KA50X20 screws.

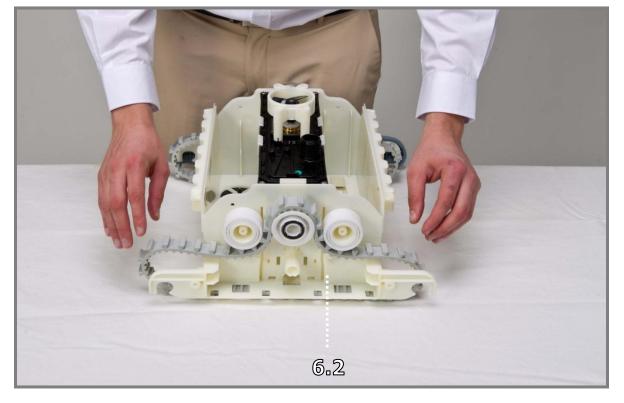
Step 5.9 Make sure the side panel clips are in their places as shown in the picture



6. Assembling the driving system and Side Cover on the other side of the robot

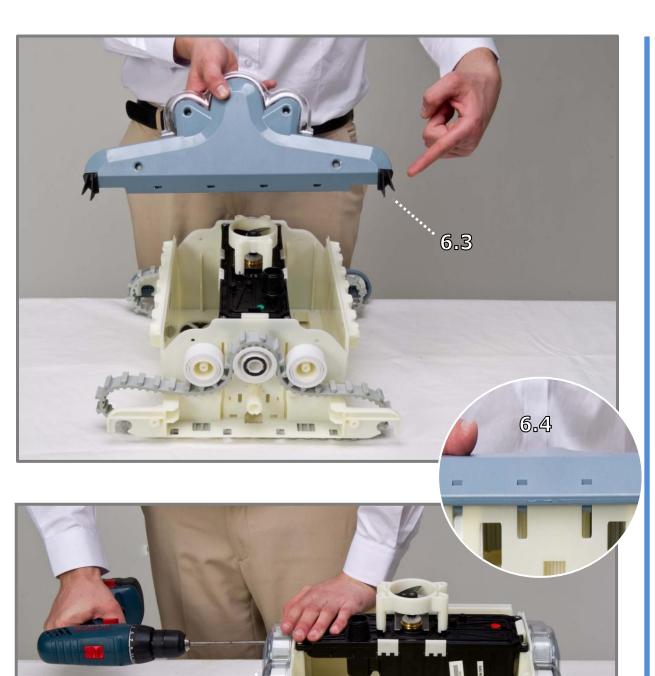


Step 6.1Place the guide wheels and pulley on the other side of the frame.



Step 6.2 put the track in place as shown.





Step 6.3Assemble the side panel with the fins facing out.

Step 6.4
Make sure the side panel clips are in their places as shown in the picture

Step 6.5Secure the side panel in place with 4 KA50X20 screws.



6.5

7. Assembling the Floating Cable

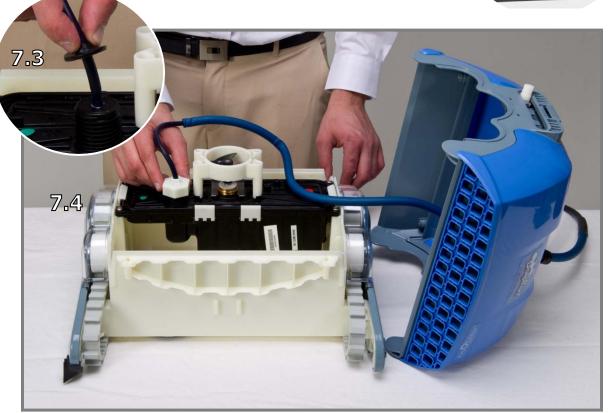


Step 7.1Insert the float

Insert the floating cable to the motor unit.

Step 7.2

Connect the cable's retrofit to motor unit (mind the slot shape) and press it firmly.



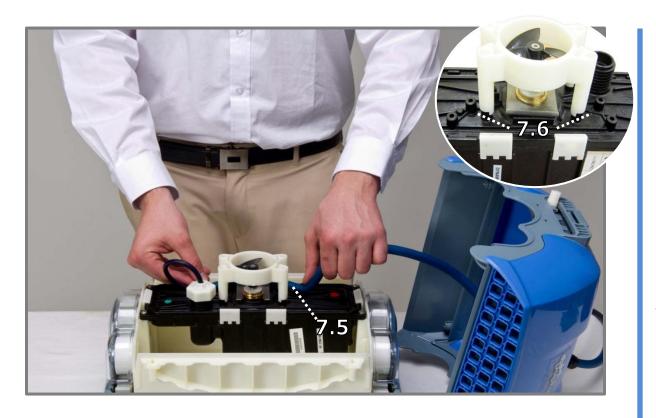
Step 7.3

Press the seal firmly to the terminal.

Step 7.4

Tighten the nut properly by hand.





Step 7.5Position the floating cable on the motor unit.

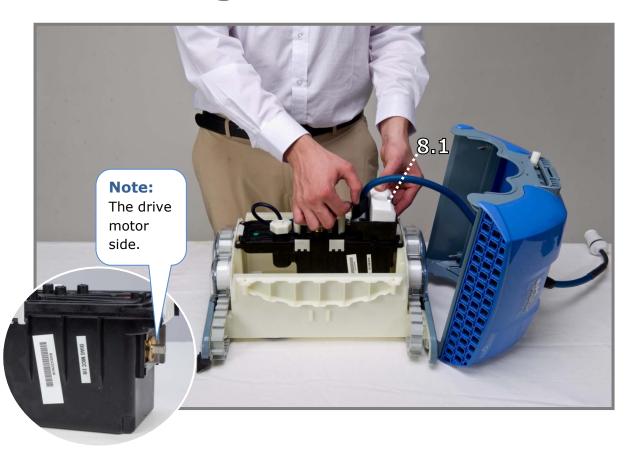
Step 7.6The cable position on the motor unit.



Step 7.7Secure the cable holders with 4X KA50X12 screws.



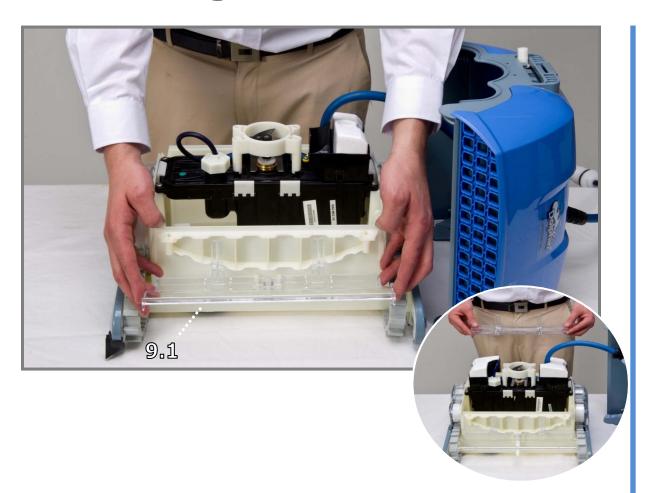
8. Positioning the Float



Step 8.1
Place the float on the motor unit, on the drive motor side as shown.



9. Positioning the Brush Covers



Step 9.1Position the 2 brush safety covers.



10. Assembling the Outer Casing



Step 10.1 Place the outer casing on the frame.

Step 10.2Secure the outer casing to the frame with 4X KA50X20 screws.



11. Assembling the Impeller Cover



Step 11.1
Place the cable support in its place on the outer casing before closing the impeller cover.

Step 11.2Position the impeller cover diagonally on the outer casing.



Step 11.3Secure the impeller cover with a KA50X12 screw.



12. Assembling the Handle



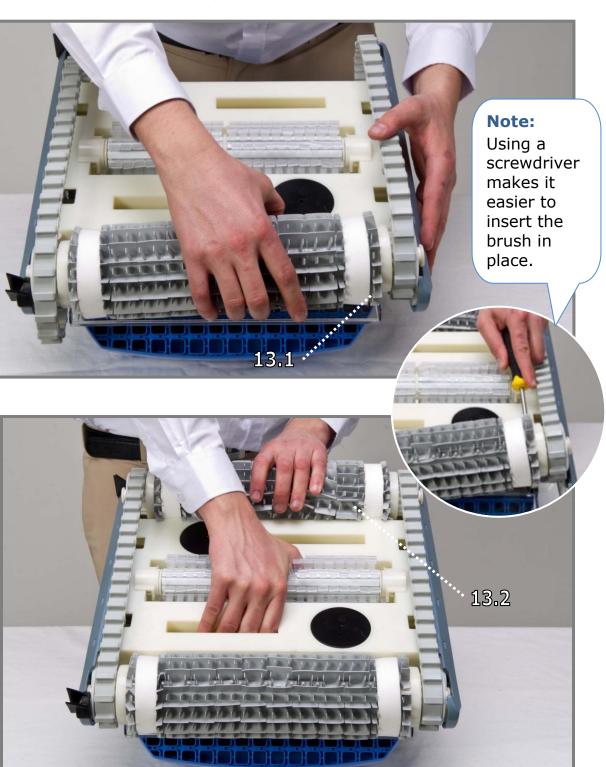
Step 12.1 Position the handle.



Step 12.2Secure the handle in place with 2
KA50X20 screws.



13. Assembling the Brushes



Step 13.1 Place one brush in place.

Step 13.2
Place the second
brush in its place
by pulling it
strongly towards
you.



Table of Contents

1. Dismantling the Handle	2
2. Dismantling the Impeller Cover	
3. Dismantling the Outer Casing	4
4. Dismantling the Cable	
5. Disassembling the Motor Unit	
6. Dismantling the Side Panels	
7. Dismantling the Driving System	
8. Dismantling the Brushes	
9. Dismantling the Diaphragms	
7. DISHIGILLING LIE DIGDINGUINS	IU



1. Dismantling the Handle



Step 1.1Unscrew the 2
screws holding the handle in place.



Step 1.2Take the handle off.



2. Dismantling the Impeller Cover



Step 2.1Unscrew the screw holding the impeller cover in place.



Step 2.2Lift the impeller cover up from one side and then take it off.



3. Dismantling the Outer Casing



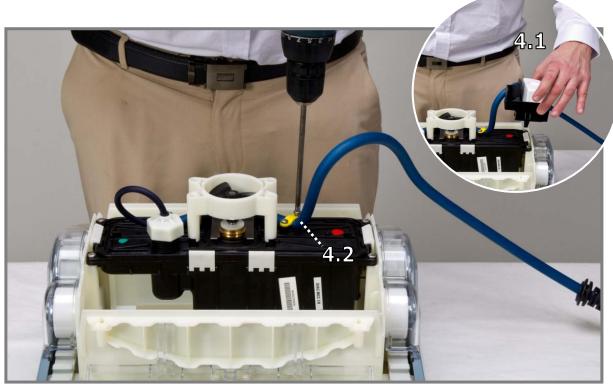
Step 3.1Unscrew the 4 screws holding the outer casing in place.

Step 3.2Remove the black grommet before taking off the outer casing.

Step 3.3
Hold the outer casing on both sides and pull it up.

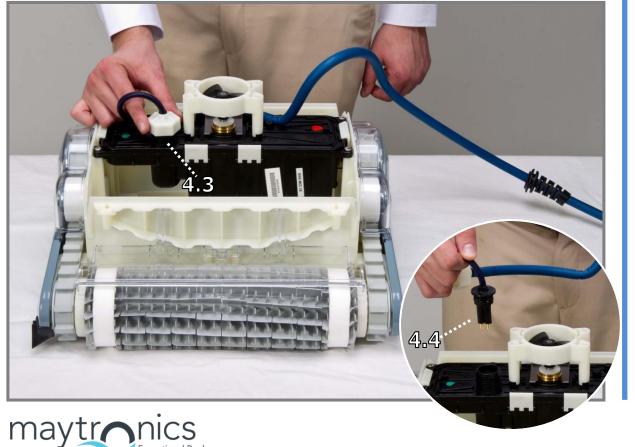


4. Dismantling the Cable



Step 4.1Remove the float from the motor unit.

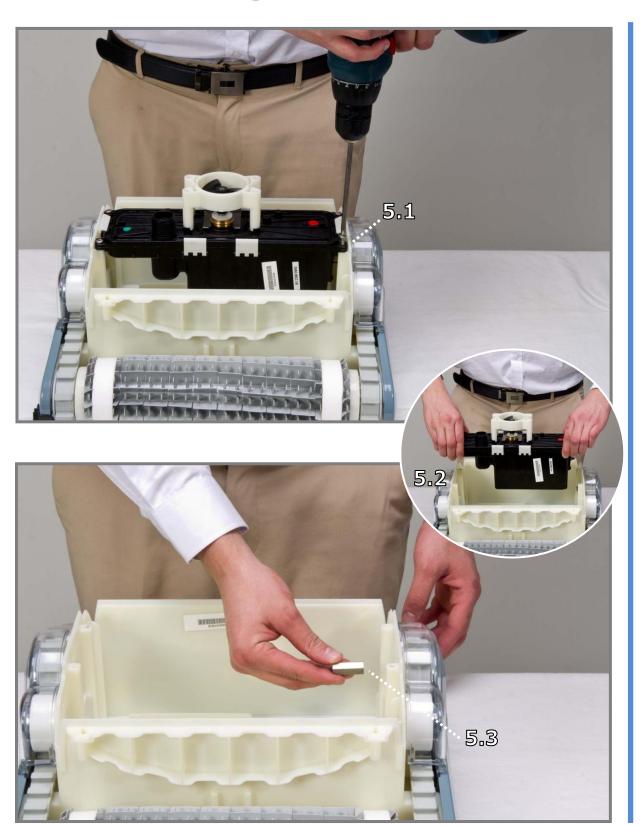
Step 4.2Unscrew the 4
screws securing the cable holder.



Step 4.3Unscrew the cable from the motor unit.

Step 4.4 Unplug the cable.

5. Disassembling the Motor Unit



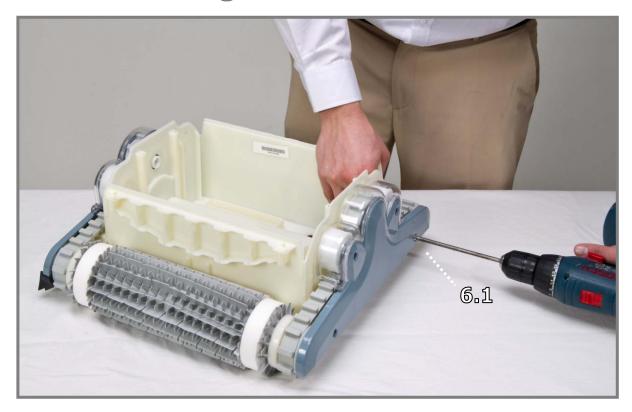
Step 5.1Unscrew the 4 screws securing the motor unit to the frame.

Step 5.2Remove the motor unit

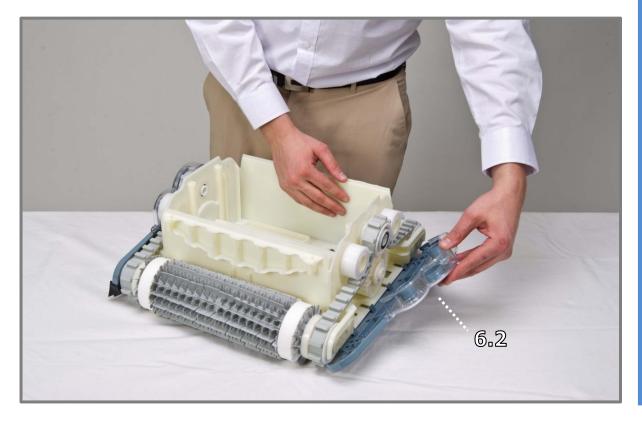
Step 5.3Remove the hexagon adapter.



6. Dismantling the Side Panels



Step 6.1Unscrew the 4 screws holding each panel in place.



Step 6.2Pull the side panels off.



7. Dismantling the Driving System



Step 7.1Remove the pulley together with the track from one side of the robot.

Step 7.2Remove guide wheels.

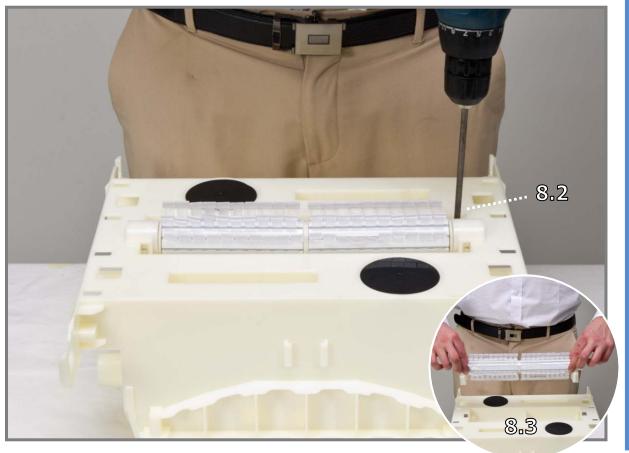
Step 7.3
Remove the pulley together with the track and Active Brush's driving wheel from the other side of the robot.



8. Dismantling the Brushes



Step 8.1Remove the brushes.

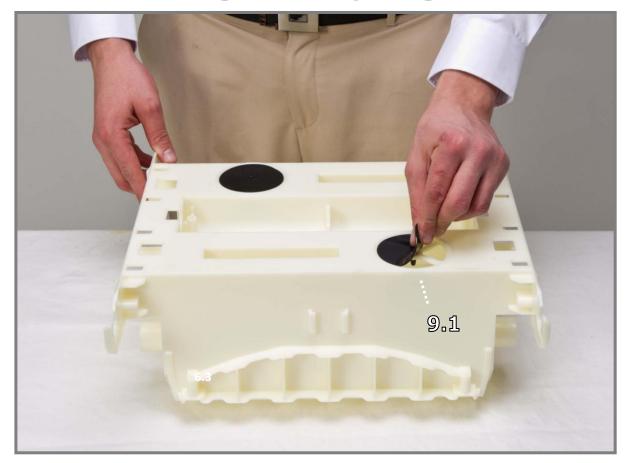


Step 8.2Open the 4 screws holding the active brush in place.

Step 8.3Remove the Active Brush.



9. Dismantling the Diaphragms



Step 9.1Remove the 2 diaphragms.

